

Title: SECCHI FITS Header Keyword Definition

Interface Category: Ground Software

Applicable Subsystems: SECCHI Ground Data Systems, SECCHI Flight Software, SECCHI I&T Team

Purpose: This document defines the data type, range of values, and description for each of the keywords that will be included in the SECCHI FITS image header. The SECCHI science team, flight software team, and I&T lead will review this to make sure that keywords required for instrument testing, instrument calibration, hardware-in-the-loop mission simulations, and science operations, are present. Note: The content of this document is the same as (and supercedes) the document titled "Definition of SECCHI Level 0.5 FITS Header" or the appendix of the SECCHI Data Management Plan.

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Revision History

Rev	Document Date	Author	Change Description		
0 d1	11/9/01	Nathan Rich	Initial Release as SICM 06-0020.		
0 d2	1/16/02	Nathan Rich	Released for comment		
0 d3	9/30/02	Nathan Rich	Incorporate FITS definition with comments received into SICM. Renumbered/released as SICM 07-0007		
0 d4	10/29/02	Nathan Rich	Make consistent with SECCHI Data Processing Plan appendix		
0 d5	11/7/02	Nathan Rich	Modify filename; add CCD eval. Keywords; other changes		
0 d6	12/19/03	Nathan Rich	Added or changed FILEORIG, DATE-OBS, GAINMODE, OFFSET, WGA_FILE, CLR_TBL, READ_TBL, LAMP, POLAR, EXPCMD, EXPCLRO, CLR_TIME, READTIME, JITRMAX, PCj_i		
0 d7	7/30/04	Nathan Rich	Compare to FSW image header		
0d8	2/3/05	Nathan Rich	Update keywords		
0d9	10/7/05	Nathan Rich	Incorporate comments from Bill Thompson (4/28/05, 6/05) and Jeff Hall (7/7/05)		
1.0	10/11/05	Nathan Rich	Add DATE_CLR, DATE_RO		
1.1	10/25/05	Nathan Rich	Change location of hdractualspecs.htm		
1.5	2/14/06	Nathan Rich	Use (next) cvs rev number; rename BIAS, LED, GAIN, DATE-MID		
1.6	7/6/06	Nathan Rich	Add EUVI extended header keywords from J-P Wuelser; Incorporate changes from FITS Header meeting on 6/2/06		
1.7	7/7/06	Nathan Rich	Add keywords for HI team requested in email from C.Eyles dated 6/18/06		
1.8	8/8/06	Nathan Rich			
1.9	9/11/06	Nathan Rich	Update X(Y)CEN, RECTIFY, S1(2)COL, MASK, CROTA; remove JITTER, JITRMAX, OBJECTID		
1.10	9/11/06	Robin Colaninno	Added column to indicate if keyword will be in the Level 1.0 and higher headers		
1.11	1/24/07	Nathan Rich	FILENAME: A=2 (RT); corrected SUM keyword definitions; BLANK type; updated TBL, FILE keyword definitions; POLAR definitions for level-2 products; added TIMGCTR; VCHANNEL for Level-0; corrected BIASMEAN definition; renamed SOURCE to be DOWNLINK; added AZP TYPEs for HI; added PV2_1		
1.12	3/27/07	Nathan Rich	Filename L=0, A=p,B,A,P; DIV2CORR; BLANK; RECTROTA, DSTART1(2), DSTOP1(2); PV2_1A; clarified EXPTIME, BIASMEAN, CRVAL, CTYPE1A, ATT_FILE, DSATVAL, MISSLIST		
1.13	6/14/07	Nathan Rich	Added SC_YAW, SC_PITCH, SC_ROLL; FILENAME, MISSLIST defn change; CEB_T, CRPIXi, CRVALj CRVALjA, CTYPEiA description clarifications;		
1.14	9/19/07	Nathan Rich	Added SC_YAWA, SC_PITA, SC_ROLLA, INS_X0, INS_Y0, INS_R0. Updated definitions of SUMMED, CCDSUM, EVCOUNT, EVROW(COL), OFFSETCR, SC_YAW, SC_PITCH, SC_ROLL, MISSLIST		

Rev	Document Date	Author	Change Description
1.15	7/1/08	Nathan Rich	Clarified definition of CCDSUM, PiCOL, PiROW; increased EXPTIME precision in extended header definition and updated to reflect def_secchi_ext_hdr.pro,v 1.11; clarified ATT_FILE suffix
1.16	11/20/08	Nathan Rich	Corrected CROTA definition
1.17	4/27/10	Nathan Rich	Clarify CMDOFFSE, SUN_TIME
1.18	4/27/10	Nathan Rich	Sort keywords alphabetically
1.19	4/5/2012	Nathan Rich	add CRITEVT keyword (beacon only); redefine EVCOUNT, EVENT, EVROW(COL); DATE means last mod; change VERSION definition; clarify timing of position values
1.20	6/26/2012	Nathan Rich	Add CALFAC keyword; update FILENAME
<u>1.21</u>	2/26/2014	Nathan Rich	Update FILENAME definition for HI L1 & L2; updated coordinate system discussion and references

DEFINITION OF SECCHI Level 0.5 FITS HEADERS

OVERVIEW

MAIN HEADER

The items in the box are part of the pre-flight image header. Keywords are to be added as they become applicable. *Rows in ITALICS represent keywords that are not expected to be in use after launch.*

1. Minimum Header:

All images taken with SECCHI cameras should have this header information, from camera level testing onward.

2. Configuration Info:

Information identifying configuration; primarily for IandT, but can be for flight use.

3. Misc. Camera/CCD values:

Values specific to CCD and camera characteristics. Should be in all images from camera level testing onward.

4. Used from telescope level testing onward:

These keywords are applicable only if mechanisms apart from the camera are used in taking an exposure.

5. Housekeeping Parameters:

Ancillary information indirectly related to an image.

6. Software-Dependent Values:

These values are dependent on on-board image processing, nominally the SECCHI Flight Software.

7. FPS values from EUVI Extended Header

8. Computed from information external to the image, on the ground:

These values have ancillary information about spacecraft position, attitude, etc. This includes coordinate system definition. All attitude and orbit information is computed from DATE-END (end of exposure) for HI, and DATE-OBS (beginning of exposure) for SCIP telescopes.

9. Computed from image values, on the ground:

Values computed from the image but not in the FSW are included here.

10. HISTORY:

Examples of history field values.

11. Simulation Images

Values used for images generated from simulations.

SECCHI FITS EXTENSION

Information about individual exposures used to compute a single image from a sequence is contained in an ASCII table extension to the FITS header.

12. Extension Table Column (Field) Definitions

These are the values that will be recorded for each exposure.

13. Keywords for FITS Extension

Each column in a FITS extension has its own set of keywords to define the type of value.

TABLE DESCRIPTION

The following table has 6 columns: KEYWORD, TYPE, VALUES, DESCRIPTION, SOURCE, and L-1?:

KEYWORD gives the name of the FITS keyword and may be up to 8 characters.

TYPE refers to the data type of the header value:

- S String (max 68 chars)
- I Integer
- R Real
- L Logical (ASCII char, T or F)

The size of the data depends upon the data type. For example S*2 is a 2 character string, whereas I*2 is a 2 byte integer (16 bits).

VALUES shows the range of values that the KEYWORD can take.

DESCRIPTION gives a short description of the keyword. At the end of the description is a reference to a Flight Software (FSW) requirement, if any. (NOTE: FSW requirement numbers not up-to-date as of 9/10/02.)

SOURCE gives information about where the keyword value comes from.

L-1? Has an X if the keyword is included in the Level-1 header generated by secchi_prep.pro.

IMPLEMENTATION

This document is implemented in the SolarSoft procedures def_secchi_hdr.pro (v TBD) and make_scc_hdr.pro (v TBD). Translations of discrete values for various states can be found in def_scc_enums.pro.

References

- 1. "Coordinate Systems for Solar Image Data",
 - http://orpheus.nascom.nasa.gov/~thompson/papers/coordinates.pdf
 - 1.1. SECCHI Coordinate System Discussion
 - 1.1.1. Image <u>coordinatess</u>: <u>Primary choiceDefault</u> is Helioprojective Cartesian; <u>secondary coordinate (A) is RA-DEC also will be included</u>. <u>Ecliptic and</u> <u>Helioecliptic are possible if desired</u>. <u>A third coordinate included is Carrington</u> (CRL? OBS).
 - 1.1.2. Position: Heliocentric Inertial (HCI): Z=Solar rotational axis, X=Solar ascending node on ecliptic of J2000. Header may also contains HEQ, HEE and GCI-HAE position coordinate numbers, depending on interest.
 - 1.1.3. Factors/requirements in selection of coordinate system:
 - 1.1.3.1. Easily correct for B angle
 - 1.1.3.2. Identify central meridian
 - 1.1.3.3. Easily correct for differences in solar radius from distance
 - 1.1.3.4. Ecliptic
 - 1.1.3.5. Ascertain position relative to planets
 - 1.2. Possibilities suggested so far:
 - 1.2.1. EIT and LASCO (implicitly) use Helioprojective Cartesian with TAN projection
 - 1.2.2. RA and DEC with TAN projection
- 2. "Definition of the Flexible Image Transport System (FITS)", http://archive.stsci.edu/fits/fits_standard/fits.gsfc.nasa.gov/fits_standard.html
- 3. "Definition of LASCO Level 1 FITS Header Keywords", http://lascowww.nrl.navy.mil/level_1/level_1_keywords.html
- 4. "SSW Keyword/Tag Definitions", http://www.lmsal.com/solarsoft/ssw_standards.html
- 5. "A User's Guide for the Flexible Image Transport System (FITS)", http://fits.gsfc.nasa.gov/documents.html#Uguidearchive.stsci.edu/fits/users_guide/
- 6. Detailed proposal for representing world coordinates in FITS (http://fits.gsfc.nasa.gov/fits_wcs.html/www.aoc.nrao.edu/~egreisen/inFITS.html):
 - 6.1. *Representations of world coordinates in FITS* by Greisen and Calabretta, 31-December-2001.
 - 6.2. *Representations of celestial coordinates in FITS* by Calabretta and Greisen, 12-December-2001.
 - 6.3. *Representations of spectral coordinates in FITS* by Greisen and Valdes, 31-December-2001
- 7. SOHO object list http://Orpheus.nascom.nasa.gov/object.dat
- 8.7.M.Fraenz and D.Harper, *Heliospheric Coordinate Systems*, Plan.Space Sci., 50, 217-233 (Feb 2002) http://www.mps.mpg.de/homes/fraenz/systems/
- 9.8.D.Wang, SECCHI Science Operations Manual, http://stereo.nrl.navy.mil/cnsrtm/<u>docs/</u>SECCHISciOpsManual.<u>docpdf</u>
- <u>10.9.</u> J.Chiralo, N.Rich, SECCHI Science Header Actuals Description, http://stereo.nrl.navy.mil/cnsrtm/docs/design/science/secchihdractualsspec.htm



MAIN HEADER

	KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1?
	ANTENNA	S*12	Any	Antenna which received (most) of the packets for this image	from FrontEnd ID used in playback	
	APID	I*2	List	Application ID for the telemetry from which this image is generated.	SEB hdr: derived from filename	
	ATT_FILE	S*36	Any	Source of pointing info (such as kernel file from which S/C attitude information is derived). There is a suffix "+eGT" where +GT indicates GT data used for pointing, and e= 0 if no error, otherwise nonzero error code: 7 : invalid observatory 3 : error reading GT calibration file. 2 : no roll update: spice/icy not available 1 : outdated GT calibration data	<pre>get_stereo_spice_ker nel.pro, scc_[gt2]sunvec.pro</pre>	X
	BIASMEAN	R*4	Any	As of BLD501 (12/06), The bias is the average of 1 column depending upon the amount of CCD summing: <u>Col</u> 1x1 25 2x2 12 4x4 6 8x8 3 (NOTE: This is invalid for readouts that have P1COL > 1.)	SEB hdr: meanbias	х
	BIASSDEV	R*4	Any	Standard deviation of column used to compute BIASMEAN	SEB hdr: stddevbias	Х
	BITPIX	I*2	16,32,- 32, -64	Number of bits per pixel	FITS	Х
]	BLANK	I*2	0, for HI= xFFFF	Value of missing or masked data.	constant	х
	BSCALE	R*8	Any	For FITS use only. If missing, then assumed to be 1: output data = FITS data * BSCALE + BZERO	derived	Х
	BUNIT	S*20		Physical unit of array values (after BZERO and BSCALE, if present, are applied)	definition	Х
	BZERO	R*8	Any	For FITS use only. If missing, then assumed to be zero	derived	Х
	CADENCE	R*4	Any	Number of seconds between exposures/sequences for the current observing program/OBS_ID (not individual exposures in a sequence). Is zero if no previous instance is found. (FSW 410?)	Computed in pipeline	Х
	CALFAC	R*4	0,1,any	Photometric calibration factor applied to image in SECCHI_PREP (0.0 is none applied)	get_calfac.pro	Х
	CAM_STAT	I*1	0-3	enum CAMERA_PROGRAM_STATE (1=CAMERA_READY)	SEB hdr: ccdintfstatus	
	CAMERA	S*?	List	Model of camera electronics used to acquire image (ie, 'Talktronics IDS-2100', 'RAL Prototype', 'RAL DM')	user input	
	CCD_COAT	S*20	List	Description of coating on CCD (ie, 'None', 'AR',)	user input	
	CCD_ID	<i>S*?</i>	Any	Identification number of CCD	user input	

KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1
CCDSUM	R*4		<pre>(sumrow + sumcol)/2.0 unsummedvalue=value/(2^(IPSUM-1))^2. Remember to account for DIV4 in IP list (always done in secchi_prep).</pre>	SEB_hdr: derived from sumrow(col)	Х
CDELTj	R*8	Any	The width and height of a pixel in data units, where units are specified by CUNITj (Same as PLATESCL)	ground table	Х
CDELTjA	R*4	Any	Same as CDELTj except degrees	ground table	Х
CEB_STAT	I*1	0-20	CEB-Link-status (enum CAMERA_INTERFACE_STATUS) (0=SUCCESSFUL_RESPONSE)	SEB hdr: cebintfstatus	
СЕВ Т	R*2	any	CEB internal temperature (1 hour median)	ICSCIP/HIHKTEMP	
CLEARTIM		Any	Duration (sec) of clear operation	lookup table	
CLR_TBL	I*1	0-7	Table used for clear (key in WGA file or READFILE) Table filename and version number in field comment.	SEB hdr: clrTableID, comment from READFILE	
CMDOFFSE	R*4	Any	Offset applied to DATE-CMD when image is scheduled onboard (Seconds)	SEB hdr: lightTravelOffsetTim e	
COMMENT	S*71		Describe method of deriving DATE-OBS	IDL pro	Х
COMMENT	S*71	→	'FITS coordinate for center of 1024x1024 image is (512.5,512.5).'	constant	Х
COMMENT	S*71		Comments. Can be repeated	varied	Х
COMMENT	S*71	Any	<i>Observer will have ability to input comments into FITS header</i>	proc or user input	
COMPFACT	R*4	Any	Actual compression factor without packet overhead	derived from decompression program output or file sizes	Х
COMPRSSN		5-17	Code indicating the algorithm used in compressing the data (FSW 215,410)	SEB hdr: from ipCmdLog + comment from cnvrt_ip.dat	Х
CONSHEAT	L	Τ(F)	All loops do (not) have same base heating rate (Simulated images)	user input	
CONTAMIN	L	T(F)	CCD is considered contaminated	user input	
COSMICS	I*4	Any	Number of pixels removed from image by cosmic ray removal algorithm in FSW (if image is from a sequence, then the mean) (FSW 217,411,416)	HI image, if requested	х
CRITEVT	S*6	Охнннн	Value of critEvent word in hex chars. EV* keyword values derived from the beacon image hdr; non-beacon images have no IP evtDetect information in this word.	SEB basehdr (beacon only): critEvent	
CRLN_OBS	R*4	0-360	Carrington Heliographic longitude of observer (degrees) at DATE-OBS (of the last exposure in sequence).	SPICE	Х
CRLT_OBS	R*4	???	Carrington Heliographic latitude of observer (degrees)	SPICE	Х
CROTA	R*4	Any	Rotation angle of solar north of image about axis perpendicular to the plane of the rectified image. Specified in degrees CW relative to the Y direction. (Superceded by PCj_i) (Sign is opposite that of input to rot.pro.)	SPICE. Source file in comment.	Х
CRPIXi	R*4	Any	The pixel coordinates of sun center (EUVI), occulter center (COR), or CCD center (HI).	Pre-flight and on- orbit Calibration	X

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KEYWORD		VALUES	DESCRIPTION	SOURCE	L
	Е	_			
CRPIXIA	R*4	Any	Same as CRPIXi	Pre-flight Calibration	Х
CRVALj	R*4	Any	The reference frame data coordinates of CRPIX1(2). If the pixel coordinates specify the origin of the coordinate system (sun center), then set CRVAL1 and CRVAL2 to zero. (arcsec)	SPICE	Х
CRVALjA	R*4	Any	R.A.(Dec.) coordinates of CRPIXiA on celestial sphere	SPICE	Х
CS	R*4	Any	Synchrotron current (units?)	user input	
CTYPE1	S*8	HPLN- TAN or HPLN- AZP (HI)	A string value representing the type of each coordinate axis: Helioprojective Cartesian with Gnomonic (TAN) Projection. CTYPE1 is for x (westward angle) axis (θ_x) . For HI projection is Perspective Zenithal (AZP)	definition	х
CTYPE1A	S*8	RA TAN or RA AZP (HI)	A string value representing the type of each coordinate axis (RA=Right Angle= Geocentric Equatorial Inertial). Projection CTYPE1 is for x (westward angle) axis (θ_x). For HI, projection is Perspective Zenithal (AZP)	constant	X
CTYPE2	S*8	HPLT- TAN or HPLT- AZP (HI)	Helioprojective Cartesian with Gnomonic (Perspective Zenithal) Projection for y (northward angle) axis (θ_y) .	definition	X
CTYPE2A	S*8	DEC TAN or DEC AZP (HI)	Projection for y (northward angle) axis (θ_y) (DEC=Declination= Geocentric Equatorial Inertial).	constant	X
CUNITj	S*8	arcsec, deg for HI	The units of the coordinates along axis j.	constant	Х
CUNITjA	S*8	deg	The units of the coordinates along axis j.	constant	Х
DATAAVG	R*4	Any	Average value of the image	derived	Х
DATAMAX	R*4	Any	Maximum value of the image	derived	Σ
DATAMIN	R*4	Any	Minimum value of the image, including the bias	derived	Σ
DATAP01	R*4	Any	Intensity of 1st percentile of image	derived	Σ
DATAP10	R*4	Any	Intensity of 10th percentile image	derived	Σ
DATAP25	R*4		Intensity of 25th percentile of image	derived	Σ
DATAP75		Any	Intensity of 75th percentile of image	derived	Σ
DATAP90	R*4	Any	Intensity of 90th percentile of image	derived	Σ
DATAP95		Any	Intensity of 95th percentile of image	derived	Σ
DATAP98	-	Any	Intensity of 98th percentile of image	derived	Σ
DATAP99	R*4	Any	Intensity of 99th percentile of image	derived	Σ
DATASAT	I*4	Any	Number of saturated values in the image	derived	X
DATASIG	R*4		Standard deviation in computing the average	derived	X
DATAZER DATE	I*4 S*23	Any Any	Number of zero pixels in the image Date of file last modification, in CCSDS standard format (UTC): "1996-05- 21T17:28:48.208"	derived IDL	<u>}</u>
DATE-AVG	S*23	Any	Date/time of midpoint of the exposure(s) (UTC standard)	midpoint between DATE-OBS and DATE- END	Х

KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1
DATE-CLR	S*23	Any	Time of start of clear operation	SEB hdr: actualCCDclearStartT ime	
DATE-CMD	S*23	Any	uploaded target time (UTC) of (first) exposure	SEB hdr: cmdExpTime	
DATE-END	2*23	Any	Date/time of end of (last) exposure	SEB hdr: derived from actualExpTim and actualExpDuration of (last) image	х
DATE-OBS	S*23		Date and time of the start of the (first) opening of the shutter or CCD readout, whichever comes first (UTC): 2006-05- 20T00:40:05.407 (accuracy level of time known from HISTORY or COMMENT)	SEB_hdr: actualExpTime	х
DATE-RO	S*23	_	Time of start of readout	SEB hdr: actualImageRetrieveS tartTime	
DCS	R*4		Synchrotron current at diode measurement	user input	
DETECTOR	S*12	R1,COR2	Name of the telescope or devel. camera within SECCHI: Talktronics, RAL, EUVI, COR1, COR2, HI1, HI2, GT	SEB_hdr: derived from telescopID	х
DIODCOAT	I*2?	List?	Diode coating	user input	
DIODDESC	<i>S*?</i>	List	Description of diode used (ie, 'AXUV- 100AL')	user input	
DIODFILE	S*?	Any	Name of file which contains diode counts	user input	
DIODSTEP	I*2	Any	Step of instrument used to control diode wavelength, from which the actual diode wavelength is derived	user input	
DIODWVLN	?	?	Wavelength of diode in Angstroms or color?	user input	
DISTCORR	L	F(T)	True if a platescale distortion correction has been applied to the data. Implemented 2008/04/30.	secchi_prep	
DIV2CORR	L	F(T)	True if there is a correction for IP Div2 applied to the image	secchi_reduce.pro	
DOORSTAT	I*1	0-255	Telescope door state (2=OPEN, 0=CLOSED) (FSW 411?,424?,442) String equivalent in keyword comment	SEB hdr: derived from actualDoorPosition	
DOWNLINK	S*4	RT, SSR1, SSR2, SWX	How the image came down	derived from filename/APID and ground table	
DSATVAL	R*4	Any	Value above which data is not valid (too nonlinear): HI is 14,000*N_IMAGES*[2^(SUMMED-1)]^2, COR1 is 15,000, TBD by COR2, EUVI.	constant	х
DSTART1(2)	I*2	151	Indicates the first column (row) of image area on the data array.	R1COL(ROW)	
DSTOP1(2)	I*2	64209 8		R2COL(ROW)	
DSUN_OBS	I*4	any	Distance of observer from sun center (meters) at DATE-OBS (of the last exposure in sequence).	SPICE	х
EAR_TIME	R*4	Any	Time(Sun to Earth) - Time(Sun to S/C) (Seconds)	SPICE/ephemeris	Х

KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1?
ENCODERF	I*2	0255	Encoder reading from filter wheel; nominal range is 0-179, but FW is nominally disabled which results in 255	SEB hdr: actualFilterPosition	х
ENCODERP	I*1	0143	Encoder reading from polarizer (0143)	SEB hdr: actualPolarPosition	Х
ENCODERQ	I*1	023	Encoder reading from quadrant selector (023)	SEB hdr: actualPolarPosition	Х
END			Last keyword in the FITS header	na	Х
EPHEMFIL	S*36	Any	kernel file from which ephemeris coordinates are derived	<pre>get_stereo_spice_ker nel.pro</pre>	Х
EVCOUNT	S*5	′0′ — '127′	Counter of times evtDetect has been run. Last known value. (rollover at 128)	beacon SEB hdr: critEvent	Х
EVENT	L	Τ(F)	True if image taken between and including event trigger (SSR2 disable) and SSR2 re- enable. (FSW 413,424?) True means no images are being recorded on SSR2.	derived from beacon critEvent	Х
EVROW(COL)	I*2	0-63	Y(X)- block coordinate of centroid of triggered blocks in RECTIFIED image. Starts at 0.(FSW ???)	<pre>beacon SEB hdr: critEvent (COR2 only)</pre>	х
EXPCLRO	R*4	Any	Length of time between start of CCD clear operation and readout (seconds) (FSW ???)	???	
EXPCMD	R*4	Any	Sum of commanded time [between open and close of shutter (seconds) or between estimated end of clear and begin of readout] for each of N_IMAGES exposures.	<pre>SEB hdr: (cmdExpDuration + cmdExpDuration_2) * 1.024e-3, or 2.0e-3 for dark/HI</pre>	
EXPOSTBL	S*40	filenam e	Exposure and mechanism position table used (<directory \$scc_data<br="" loads="" or="" rel="" to="">>/filename, rev number appended if different than original build).</directory>	hk_events in database	
EXPOUT	R*4	Any	Length of time, shutter close to camera readout (seconds) (FSW ???)	???	
EXPTIME	R*4	Any	Time between open and close of shutter (seconds); if > 1 exposure, then the sum. For type DOUBLE, it is the average. For L=1+, use -1. (individual exptimes in header extension) (FSW 410, 423)	<pre>SEB_hdr: (actualExpDuration , actualExpDuration_2) * 4e-6</pre>	Х
EXTEND	L	T(F)	Indicates that there is (not) an extension.	pipeline	Х

	KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1?
	FILENAME	E S*25	>	Name of the FITS file:	SEB_hdr: derived	х
				yyyymmdd hhmmss LATTS brXX.fts	from cmdExpTime,	
				Format as follows:	platformID,	
				S = Spacecraft (A,B,C)(c is for anything	telescopID,	
				that is not associated with one or the	imageType	
				other s/c);	5 11	
				TT = a string representing telescope or		
				camera: eu=EUVI, c1=COR1, c2=COR2, h1=HI1,		
				h2=HI2, gt = GT, tk=Talktronics, ra=RAL		
				development camera,;		
				A = C(calib), 2(RT), 3(RT+SSR1), 4(SSR1;		
				if HI L1+, diffuse correction and		
				photometric calibration NOT applied),		
1				5(SSR2), 7(SWX), p(percent polarized),		
				B(total brightness from polarized),		
				A(polarization angle), P(polarized		
				brightness), b(HI diffuse source correction		
				and MSB units), t(HI diffuse source		
				correction and S10 units);-		
				L is a character representing type of		
				image:		
1				n = Normal Image (Level-0.5)		
				m = Multiple SCIP Exposures Combined		
				onboard (Level-0.5)		
1				d = Double Image (Level-0.5)		
				k = Dark Image (Level-0.5)		
				e = LED Image (Level-0.5)		
				c = Continuous Image (Level-0.5)		
				s = Sequence Image (Level-0.5)		
				1(one) = Calibration has been applied.		
				For EUVI and COR, default this		
				includes photometric calibration has		
				been applied; units are Mean Solar		
				Brightness for COR and photons for		
1				EUVI (Level-1). For HI, no		
				calibration factor has been applied		
				and units are DN/s/CCDPIXunits		
				depend on A.		
				b = HI Level-1; units are MSB		
				2 = Some calibration has been applied AND		
				further processing, usually		
				background removal. Units depend on		
				A.		
				0(zero) = Partial calibration		
				v = Vignetting (cal);		
				brNN = (optional) NN day background used		
$\left \right $				The rest is year, month, day, hour, minute,		
				second (equivalent to DATE-CMD)		
1	FILEORIG	S*12	Any	YMDDaaaa.APT, where $Y = LSD$ of year e.g.	SEB_hdr: filename	Х
				2002 = '2'; M = Month (1 = Jan, 2 = Feb,		
				,A=Oct, B= Nov, C = Dec); DD = Day of		
				Month; aaaa = image counter & sequence		
				number in base 36; AP = APID coding (actual		
				hex ApID minus 0x400); T = telescope (for		
				S/C A, 3=EUVI 2=COR1 1=COR2 5=HI1 4=HI2;		
				for S/C B add 5)		

KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L
FILTER	S*4	OPEN,	Position of the EUVI filter (FSW	SEB hdr: derived	Х
		S1, S2,	410,411,442)	from	
		DBL		cmdFilterPosition	
FPS_CMD	L	T(F)	FPS was (not) commanded on. EUVI ONLY	SEB extended hdr:	Х
—				useFPS	
FPS ON	L	T(F)	EUVI fine pointing system (FPS) is (not)	SEB extended hdr:	Х
—			activated during exposure(s) (FSW 320,424?)	derived from	
			EUVI ONLY	actualFPSmode	
FPSDAQ1	I*4		PZT DAC square [0]	SEB extended hdr	Х
FPSDAQ2	I*4		PZT DAC square [1]	SEB extended hdr	Х
FPSDAQ3	I*4		PZT DAC square [2]	SEB extended hdr	Х
FPSDAS1	I*4		PZT DAC sum [0]	SEB extended hdr	X
FPSDAS2	I*4		PZT DAC sum [1]	SEB extended hdr	X
FPSDAS3	I*4		PZT DAC sum [2]	SEB extended hdr	X
	I*4			SEB extended hdr	X
FPSERQ1			PZT Error square [0]		
FPSERQ2	I*4		PZT Error square [1]	SEB extended hdr	X
FPSERQ3	I*4		PZT Error square [2]	SEB extended hdr	Х
FPSERS1	I*4		PZT Error sum [0]	SEB extended hdr	Х
FPSERS2	I*4		PZT Error sum [1]	SEB extended hdr	Х
FPSERS3	I*4		PZT Error sum [2]	SEB extended hdr	Х
FPSGTQY	I*4		FPS Y square	SEB extended hdr	Х
FPSGTQZ	I*4		FPS Z square	SEB extended hdr	Х
FPSGTSY	I*4		FPS Y sum	SEB extended hdr	Х
FPSGTSZ	I*4		FPS Z sum	SEB extended hdr	Х
FPSNUMS	I*4		Number of FPS samples	SEB extended hdr	Х
FPSOFFY	I*4		Y offset	SEB extended hdr	Х
FPSOFFZ	I*4		Z offset	SEB extended hdr	X
GAINCMD	I*2	0-255	Video gain setting of camera (FSW 431?)	SEB hdr: gain	
GAINMODE	S*4	HIGH,LO		SEB hdr: gainMode	
SATIMODE	5 1	W	(FSW 434)?	Sib har. guimoue	
HAEX OBS	I*4	Any	Heliocentric Ares Ecliptic Position of	SPICE	X
_		7	spacecraft in x direction (meters) at DATE-		
			OBS (of the last exposure in sequence).		
HAEY OBS	I*4	Any	" in y direction "	SPICE	Х
HAEZ OBS		Any	" in z direction "	SPICE	Х
HCIX_OBS		Any	Heliocentric Inertial Position of	SPICE	Х
		1	spacecraft in x direction (meters) at DATE-		
			OBS (of the last exposure in sequence).		
HCIY OBS	I*4	Any	" in y direction "	SPICE	Х
HCIZ OBS		Any	" in z direction "	SPICE	Х
HEEX OBS		Any	Heliocentric Earth Ecliptic Position of	SPICE	Х
		1	spacecraft in x direction (meters) at DATE-		
			OBS (of the last exposure in sequence).		
HEEY OBS	I*4	Any	" in y direction "	SPICE	Х
HEEZ OBS		Any	" in z direction "	SPICE	X
HEQX OBS		Any	Heliocentric Earth Equatorial Position of	SPICE	X
llgr_obb			spacecraft in x direction (meters) at DATE-		
			OBS (of the last exposure in sequence).		
HEQY OBS	T * 4	Any	" in y direction "	SPICE	X
HEQI OBS		Any	" in z direction "	SPICE	X
	R*4	_	Stonyhurst Heliographic longitude of	SPICE	X
HCT.N OPC	10.04	0-300	beonynatise nettographite tongteude of	DI TCE	^
HGLN_OBS			observer relative to Earth (dogroog) at		
HGLN_OBS			observer relative to Earth (degrees) at DATE-OBS (of the last exposure in		

KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1
HGLT_OBS	R*4	???	Stonyhurst Heliographic latitude (B0) of observer (degrees) at DATE-OBS (of the last exposure in sequence).	SPICE	Х
HISTORY			'Vxx dd mmm yyyy get_exp_factor, old_exp_time, bias'	IDL pros	Х
HISTORY			'Vxx dd mmm yyyy reduce_level_1,'d2nnnnn.fts','d5nnnnn.fts ''	IDL pros	Х
HISTORY			'Vxx dd mmm yyyy vigfilename.fts'	IDL pros	Х
HISTORY	S*71	Any	History. Can be repeated.	IDL pros	Х
IMGCTR	I*2	Any	Sequential counter corresponding to filename (FSW 240?)	SEB hdr: imgctr	
IMGSEQ	I*2	03276 7	Number of the image in the current sequence, starting at 0 (FSW 240?)	SEB hdr: imgseq	
INS_X0 INS_Y0	R*4	Any	Instrument offset (yaw, pitch, roll) from GT axis used to compute CRVAL.	calibration parameter	
INS_R0					
INSTRUME		SECCHI	Name of the instrument	constant	Х
IP_00_19	S*60	numeral chars	<pre>string representation of up to 20 values in ipcmdlog. Key in ops/tables/default/ipcodes.h (cnvrt_ip.dat).</pre>	SEB hdr: ipCmdLog	
IP_PROGn, n=0-9	I*2		Description of the first 10 onboard Image Processing routine(s) which produced the image, possibly from several exposures.	<pre>SEB hdr: from ipCmdLog + comment from cnvrt_ip.dat; see also ipcodes.h</pre>	
IP_TBL	S*40	filenam e	<pre>Image processing table used (<directory rel<br="">to loads/ or \$SCC_DATA >/filename, rev number appended if different than original build)</directory></pre>	hk_events in database	
IP_TIME	I*2	Any	Duration of IP operations onboard (seconds)	seb hdr: Diff .hdr and .tlr	
IPSUM	R*4	1,2,3	Number of times +1 that rows and columns are summed by onboard IP: (sebxsum + sebysum)/2.0; if fractional value, then represents factor by which image was multiplied to correct for onboard math.	<pre>ipprocessingtime SEB_hdr: derived from sebx(y)sum (sebxsum and sebysum are by definition always equal)</pre>	X
JITRSDEV	R*4	Any	Standard deviation of JITTER, computed onboard. EUVI ONLY	SEB extended hdr: derived from GT/FPS image header values ???	х
LEDCOLOR	S*1	NONE, RED, PURPLE, BLUE	Description of LED used (FSW 411,424?)	SEB hdr: derived from cmdledmode + ehkpledcolor	
LEDPULSE	I*4	any	Number of LED pulses commanded	SEB hdr: cmdLEDPulses	
LINE_CLR	R*4	Any	Time (sec) for one line during clear operation	lookup table	
LINE_RO	R*4	Any	Time (sec) for one line during readout operation	lookup table	
LONPOLE	I*1	180	Degrees (default for helioprojective coordinates)	constant	х
MASK	S*?	F(T)	A mask was not (was) applied to image.	SEB hdr: derived from ipCmdLog	х

KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1?
MASK_TBL	S*40	e	Mask table used by onboard IP (<directory rel to loads/ or \$SCC_DATA>/filename, rev number appended if different than original build)</directory 	hk_events in database	Х
MISSLIST	S*80	Any	Charlist (base34, format='(a2)') of missing blocks. The numbers are the 1D subscripts of a 34x34 array representing superpixels of the array. For ICER, list of missing or "incorrect" segments.	derived	Х
N_IMAGES	I*2	11000 +	Number of CCD readouts used to compute the image (Number of extension header rows = N_IMAGES>1)	<pre>derived from ipCmdCnt ???</pre>	Х
NAXIS	I*2	0,2,3	Number of axes in the image (0 indicates header only)	FITS	х
NAXIS1	I*2	Positiv e	Length of the first axis (columns,x)	FITS	х
NAXIS2	I*2	Positiv e	Length of the second axis (rows,y)	FITS	х
NMISSING	I*4	Any	Number of missing blocks (not including on- board masked regions) For ICER images, number of bad segments.	derived	Х
OBJECT	S*20	Any	Object observed: there are about 10 values used during I&T how this is used for flight is TBD (suggestions welcome)	user input or lookup table?	Х
OBS_ID	1*2	03276	Observing Sequence ID (number): A number that specifies an instrument setup/configuration or sequence of exposures (such as polarizer sequence); can be used to search the database for the same types of images. Corresponds with Observation ID in Planning Tool. (FSW 050)	SEB hdr: osNumber	X
OBS_PROG	S*20 ?	Any	Description of configuration or type of measurement (ie, 'Quantum E', 'Chrg Coll E',) or name of proc or JOP ID ('JOP034', see http://soho.nascom.nasa.gov/soc/JOPs/) or	STOL proc or user input or planning tool? TBD	х
OBSERVER	S*20	List	Character string identifying operator who acquired the data associated with the header	user input or lookup table?	Х
OBSRVTRY	S*8	STEREO_ [AB]	Name of the satellite. (Replaces TELESCOP keyword, which is ambiguous.)	SEB_hdr: derived from platformID	х
OBSSETID OBT_TIME	I*2 R*4	099999 Any	Observing Set ID from Planning Tool Value of the STEREO S/C On-Board Time (seconds) (FSW 043)	SEB hdr: campaignSet ???	х
OFFSET	I*2	0-1023	Offset setting of camera	SEB hdr: offset	
OFFSETCR	R*4	Any	Offset bias subtracted from image, either on ground or in SEB.	Usually from BIASMEAN	
ORIGIN	S*8	NRL GSFC UBHAM LMSAL APL	Institution where FITS file was created	proc or processing env	
P1COL P2COL	I*2		CCD column number of start(end) of CCD readout corrected for any onboard IP trimming; 1-50 are underscan pixels, 2098- 2176 are overscan pixels (FSW 212,431) (NOTE: First column is 1, not 0.)	SEB_hdr: p1(2)col	х

KEYWORD TYP VALUES E		VALUES	DESCRIPTION	SOURCE	L1?
P1ROW P2ROW	 I*2	12112	CCD row number of start(end) of CCD readout corrected for any onboard IP trimming; 1- 2048 are the utilized imaging rows (FSW 212,431)	SEB_hdr: p1(2)row	Х
PCj_i	R*4	Any	A coordinate transformation matrix; rotation (of solar north) information is included in these keywords (replaces CROTAi)	SPICE. Source file in comment.	Х
PCj_iA	R*4	Any	Same as PCj_i but for RA/DEC coordinate system	SPICE	Х
POLAR	R*4	0 357.5, 1001- 1004	Position of the polarizer, <u>degrees</u> from vertical WRT to CCD "North,"; if the image is computed from a sequence, then this is the sum of the positions during the sequence (FSW 410,411,442) (Polarizer steps in increments of 2.5 °, or 144 positions.) For TotalB or %P images: 1001 = Total Brightness 1002 = Polarized Brightness 1003 = Percent Polarized 1004 = Polarization Angle	SEB hdr: derived from cmdPolarPosition (actual is not accurate)	X
PV2_1	R*4	Any	For HI only: a parameter which encodes information about the optical properties of the telescope, and is derived experimentally.	Optical calibration	
PV2_1A	R*4	Any	= PV2_1		Х
R1(2)COL	I*2	12176	though rectification had been unnecessary. If RECTIFY is F, then this is equal to P1(2)COL.		Х
R1(2)ROW	I*2	12176		"" and P1(2)ROW	Х
RANDHEAT	L	Τ(F)	Each loop's heating function is (not) chosen randomly (Simulated images)	user input	
READ_TBL	I*1	0-7	Table used for readout (key in WGA file or READFILE) Table filename and version number in field comment.	SEB hdr: readoutTableID, comment from READFILE	
READFILE	S*24	ro*.img	<pre>Name of readout table file used by FSW. (<directory loads="" or<br="" rel="" to="">\$SCC_DATA>/filename, rev number appended if different than original build).</directory></pre>	hk_events in database	
READPORT	S*1	L,R	CCD readout port: R=Right(A), L=Left(B) (FSW 411,431) Currently all are R except EUVI-A.	lookup table	
READTIME	R*4	Any	Actual duration of CCD read-out operation	seb hdr	
RECTIFY	L	Τ(F)	Status of rectification to put ecliptic north to the top of the image		х
RECTROTA	I*1	07	Argument for IDL rotate.pro that was used, secchi_rectify.pr or would be used, indicating rotation and transposing		
RO_DELAY	R*4	Any	Time (sec) between DATE_RO and start of readout operation	lookup table	
RSUN	R*4	Any	Radius of sun (Arcseconds)	SPICE/ephemeris	Х
S1(2)COL	I*2	Any	Start (end) X-coordinates of sub-field obtained via mask, equivalent to P1(2)COL (FSW 416) IMPLEMENTATION TBD!	SEB hdr: function of mask used and P1(2)COL	Х
S1(2)ROW	I*2	Any	Start (end) Y-coordinates (FSW 416)	"" and P1(2)ROW	Х

KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1?
SC_YAW SC_PITCH SC_ROLL	R*4	-	Uncorrected spacecraft yaw (arcsec), pitch (arcsec), roll (degrees) from SPICE attitude history, using DATE-AVG. HPC system. All units degrees for HI.	<pre>get_stereo_hpc_point .pro (SPICE)</pre>	
SC_YAWA SC_PITA SC ROLLA	R*4	Any	Uncorrected spacecraft yaw, pitch, roll from SPICE attitude history, using DATE- AVG. RA-DEC system (all units degrees).	<pre>get_stereo_hpc_point .pro (SPICE)</pre>	
SCANT_ON	L	T(F)	The "move antenna" bit from the spacecraft is (not) set during the (series of) image(s).	SEB hdr: derived from preExpSCStatus and postEXPSCStatus	Х
SCFP_ON	L	Τ(F)	Fine pointing bit from spacecraft is (not) activated. (FSW 322) EUVI ONLY	SEB extended hdr: derived from actualSCFinePointMod e	Х
SCSTATUS	I*2	any	Spacecraft status message before exposure	SEB hdr: preExpSCStatus	
SEB_PROG	S*8	DARK,	Description of the type of image (observing program ID). (Equivalent to LEB_PROG on LASCO) (FSW 217,410,411,416)	SEB hdr: derived from imageType	Х
SETUPTBL	S*40	filenam e	Camera setup table used (<directory rel="" to<br="">loads/ or \$SCC_DATA >/filename, rev number appended if different than original build)</directory>	hk_events in database	
SHUTTDIR	S*3	CW CCW	Direction of motion of the shutter from the CCD's POV (FSW 424?,442?)	SEB hdr: derived from actualshutterdirecti on and ground table	
SIMBCKD	L	Τ(F)	Simulated background is (not) included (Simulated images)	user input	
SIMNOISE	L	T(F)	Photon noise is (not) included (Simulated images)	user input	
SIMPLE	L	Т	Conforms to FITS standard	FITS	Х
SPWX	L	T(F)	This image was (not) also sent down the SPWX channel.	SEB hdr: ipCmdLog	
SR	I*4	Any	Grating number of?	user input	
STGiPOS	R*4	any	position of stimtel stages during EUVI testing	<i>GPIB stage controller via proc</i>	
SUMCOL	I*1	1,2,3	Number of times +1 that columns (after rectification) are summed on CCD	SEB_hdr: sumcol, RECTIFY	Х
SUMMED	R*4	1.0-8.0	Combines summing from CCD and IP to get one number for number of rows and columns being summed on the CCD and SEB and ground. Applies to dimension only! dimension=original/(2^(SUMMED-1)),	SEB_hdr: depends on sumrow, sumcol, sebxsum, sebysum	Х
SUMROW	I*1	1,2,3	Number of times +1 that rows (after rectification) are summed on CCD	SEB_hdr: sumrow, RECTIFY	Х
SUN_TIME	R*4	Negativ e	· · ·	SPICE/ephemeris	Х
SYNC	L	T(F)	The image is (not) commanded to be synchronous with the other spacecraft.	SEB hdr: derived from sync	Х
TEMP CCD	R*4	Any	Temperature of the CCD (degrees C)	HKP tlm	
TEMP CEB		Any	HB[SCIP,HI]CEBENCLT	HKP Tlm YSI therm	1
TEMPAFT1	R*4		Temperature, Degrees C for HIBACKSTR,	HKP Tlm	l
		-	COR1ZONE2, EUVIAFTSHTR, or COR2OPHTR3		

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KEYWORD	TYP E	VALUES	DESCRIPTION	SOURCE	L1?
TEMPAFT2	R*4	Any	Temperature, Degrees C for HIFIN, COR1DOUB2, EUVIPRIMIR, or COR2RLYLNS	HKP Tlm	
TEMPFWD1	R*4	Any	Temperature, Degrees C for HIFRNTSTR, COR1TUBEOCC, EUVIENTR, or COR2ZONE2	HKP Tlm	
TEMPFWD2	R*4	Any	Temperature, Degrees C for HIBASESTR, COR1ZONE1, EUVIFWDMNT, or COR2ZONE1	HKP Tlm	
TEMPMID1	R*4	Any	Temperature, Degrees C for HIZONE1, COR1POLDOUB1, EUVIAFTMNT, or COR2FLDLNS	HKP Tlm	
TEMPMID2	R*4	Any	Temperature, Degrees C for HIZONE2, EUVISECMIR or COR2HRMRR	HKP Tlm	
TEMPTHRM	R*4	Any	Temperature, Degrees C for COR1THERM, EUVITHERM, or COR2THERM	S/C HKP Tlm	
TIMGCTR	I*2	Any	Sequential counter of images per telescope since IC(?) restarted.	SEB hdr: telescopeImgCnt	
UFOCOUNT	I*2	any	Number of flying saucers detected	The Enquirer	
VCHANNEL	VCHANNEL I*2 6 7		Virtual channel of telemetry downlink (7=Realtime or beacon, 6=Playback, 13=6+7=Level-0) (FSW 410)	pipeline environment	
VERSION	VERSION S*8 Any		Version number of SEB header. EUVI only, for files created after 2012/04/05: +'p'+ rev. of euvi_point.pro.	SEB basehdr.version	
VOLTAGE	R*4	Any	??	???	
WAVEFILE	S*24	wave*.i mg	Name of waveform table used by FSW. (<directory loads="" or<br="" rel="" to="">\$SCC_DATA>/filename, rev number appended if different than original build).</directory>	hk_events in database	
WAVELNTH		284 304	Sector (wavelength in Angstroms) of EUVI exposure (FSW 411,424?,442)	SEB extended hdr: derived from actualpolarposition	Х
WGA_FILE	S*20	*.wga	Filename of list of waveforms and tables loaded (TDS only)	swire	
XCEN, YCEN	R*4	Any	<pre>East-West (North-South) FOV center of CCD relative to sun center in CDELT1(2) units, positive West (North). X(Y)CEN is related to the above FITS keywords by: i = (NAXIS1+1)/2 - CRPIX1 j = (NAXIS2+1)/2 - CRPIX2 X(Y)CEN = CRVAL1(2) + CDELT1(2)*[PC1(2)_1*i + PC1(2)_2*j] (units = arcseconds, deg for HI)</pre>	derived	x

SECCHI FITS EXTENSION

Information about individual exposures used to compute a single image from a sequence is contained in an ASCII table extension to the FITS header. With the exception of DELTTIME, the values in the columns (fields) have the same meaning as the corresponding keywords in the main header, if the main header is for a single image. If an image consists of a single exposure, this table is optional and would have a single row. There is one row for each exposure, including the first one in the sequence.

FIELD	HEADING	HEADING VALUES DESCRIPTION	
1	DELTTIME	Any	Time (seconds) from the beginning of the first exposure. (i.e., Difference between actualExpTime of current exposure and the first exposure.) First row is always zero.
2	EXPTIME	Any	Duration of the exposure (seconds)
3	CCDSUM	Any	(sumrow + sumcol)/2.0
4	IPSUM	Any	(sebxsum + sebysum)/2.0
5	POLAR	0357.5	Commanded Position of the polarizer, degrees from vertical WRT to detector
6	SHUTTR	T(F)	Shutter was (not) commanded open during the exposure
7	ENCODER	0143	Encoder reading from polarizer (mech.actualPolarPosition2)
8	LEDCOLOR	N,R,B,P	Color of LED commanded on (FSW 411)
9	DOORSTAT	0-3	Telescope door state
10	IMGCTR	Any	Sequential counter since the last SEB reboot
11	IMGSEQ	Any	Number of the image in the current sequence, starting at 0
12	EVENT	T(F)	An event has (not) been triggered by the event detection algorithm prior to this exposure (FSW 413)
13	EVCOUNT	Any	Count level used by the event detection algorithm to detect event (FSW 413)
14	EVROW	Any	X-coordinate of event centroid (FSW ???)
15	EVCOL	Any	Y-coordinate of event centroid(FSW ???)
16	DATE_CLR	Any	Time of start of clear operation
17	DATE_RO	Any	Time of start of readout
18	COSMICS	Any	Number of pixels removed from exposure by cosmic ray removal algorithm (FSW 217,411)

Extension Table Column (Field) Definitions

The following illustrates the layout of each row in the extension table:

-DDThh:mm:ss.sss YYYY-MM-DDThh:mm:ss.sss iiiiii

Keywords for FITS Extension

KEYWORD	TYPE	VALUES	DESCRIPTION
XTENSION	S*8	TABLE	Required
BITPIX	I*2	8	Indicates printable ASCII characters
NAXIS	I*2	2	Axes are the rows and columns of the table
NAXIS1	I*2	126	Number of characters in a table row
NAXIS2	 I*2	Any	Number of exposures in the sequence (=N IMAGES)
PCOUNT	I*2	0	Required
GCOUNT	I*2	1	Required
TFIELDS	I*2	18	Number of fields in each table row
TFIELDS	1~2	10	
TBCOL1	I*2	1	Column number of first character in first field
TFORM1	S*4	F8.3	FORTRAN format of field 1: single precision floating
	~ -		point
TTYPE1	S*8	DELTTIME	Heading for field 1.
TUNIT1	S*7	Seconds	Units of field 1.
TBCOL2	I*2	10	Column number of first character in field 2
TFORM2	S*4	F10.6	FORTRAN format of field 2: single precision floating
			point
TTYPE2	S*7	EXPTIME	Heading for field 2.
TUNIT2	S*7	Seconds	Units of field 2.
TBCOL3	I*2	21	Column number of first character in field 3
TFORM3	S*2	I2	FORTRAN format of field 3: integer
TTYPE3	S*6	CCDSUM	Heading for field 3.
TUNIT3	S*2	NA	Units of field 3.
100115	D Z	INA	biits of ffeld 5.
	I*2	2.4	Column number of first character in field 4
TBCOL4		24	
TFORM4	S*2	I2	FORTRAN format of field 4: integer
TTYPE4	S*5	IPSUM	Heading for field 4.
TUNIT4	S*2	NA	Units of field 4.
TBCOL5	I*2	27	Column number of first character in field 5
TFORM5	S*2	F6.1	FORTRAN format of field 5: float
TTYPE5	S*2 S*5	POLAR	Heading for field 5.
TUNIT5	S*7	Degrees	Units of field 5.
TBCOL6	I*2	34	Column number of first character in field 6
TFORM6	S*2	A1	FORTRAN format of field 6: character
TTYPE6	S*6	SHUTTR	Heading for field 6.
TUNIT6	S*0 S*7	Logical	Units of field 6.
IUNIIO	5.7	LOGICAL	
TBCOL7	I*2	36	Column number of first character in field 7
TFORM7	s*2	I3	FORTRAN format of field 7: character
TTYPE7	S*8	ENCODER	Heading for field 7.
TUNIT7	S*8	NA	Units of field 7.
/	~ ~		
TBCOL8	I*2	40	Column number of first character in field
TFORM8	S*2	A1	FORTRAN format of field: character
TTYPE8	S*2 S*4	LEDCOLOR	Heading for field.
	S*4 S*2		Units of field.
TUNIT8	5"2	NA	
TRACT O	T - 1- 0	4.0	
TBCOL9	I*2	42	Column number of first character in field
TFORM9	S*2	I1	FORTRAN format of field: small int

TYPEPS St4 DOORSTAT Heading for field. TUNIT9 St2 NA Units of field. TBCOLIO I+2 44 Column number of first character in field TGORNIO St2 IS FORTRAN format of field. TTYPE10 St6 INGCTR Heading for field. TUNIT10 St2 IA FORTRAN format of field integer TTYPE11 St4 None Units of field. TUNIT11 St4 None Units of field. TUNIT11 St4 None Units of field. TUNIT12 St5 Column number of first character in field TFORN13 St2 IA FORTRAN format of field. TUNIT12 St7 Column number of first character in field TFORN13 St2 IA FORTRAN format of field. TUNIT12 St7 Column number of first character in field TFORN13 St2 IA FORTRAN format of field. TUNIT13 St4 FORTRAN format of field. Integer TTYPE	KEYWORD	TYPE	VALUES	DESCRIPTION
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TTYPE20 PC2_1 Heading for field.				
			PC2_1	Heading for field.
TUNIT20 NA	TUNIT20		NA	

KEYWORD	TYPE	VALUES	DESCRIPTION
TBCOL21		152	Column number of first character in field
TFORM21		F9.6	FORTRAN format of field: float
TTYPE21		PC2_2	Heading for field.
TUNIT21		NA	
TBCOL22		162	Column number of first character in field
TFORM22		F9.5	FORTRAN format of field: float
TTYPE22		CRVAL1	Heading for field.
TUNIT22		deg	for HI; arcsec for SCIP
TBCOL23		172	Column number of first character in field
TFORM23		F9.5	FORTRAN format of field: float
TTYPE23		CRVAL2	Heading for field.
TUNIT23		deg	for HI; arcsec for SCIP
TBCOL24	I*2	182	Column number of first character in field
TFORM24	S*2	I7	FORTRAN format of field: long integer
TTYPE24	S*7	COSMIC	Heading for field.
TUNIT24	S*6	Pixels	Units of field.