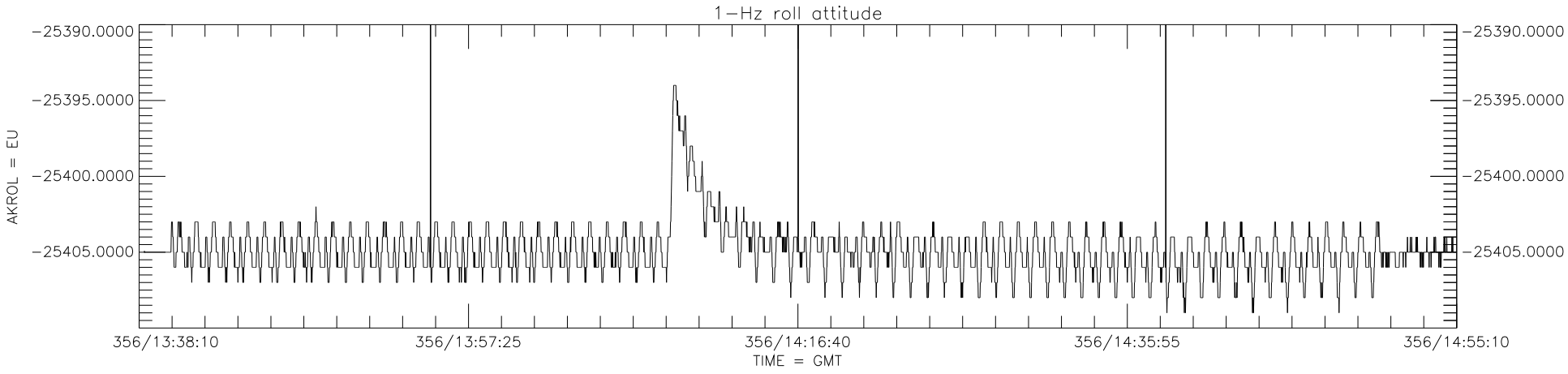
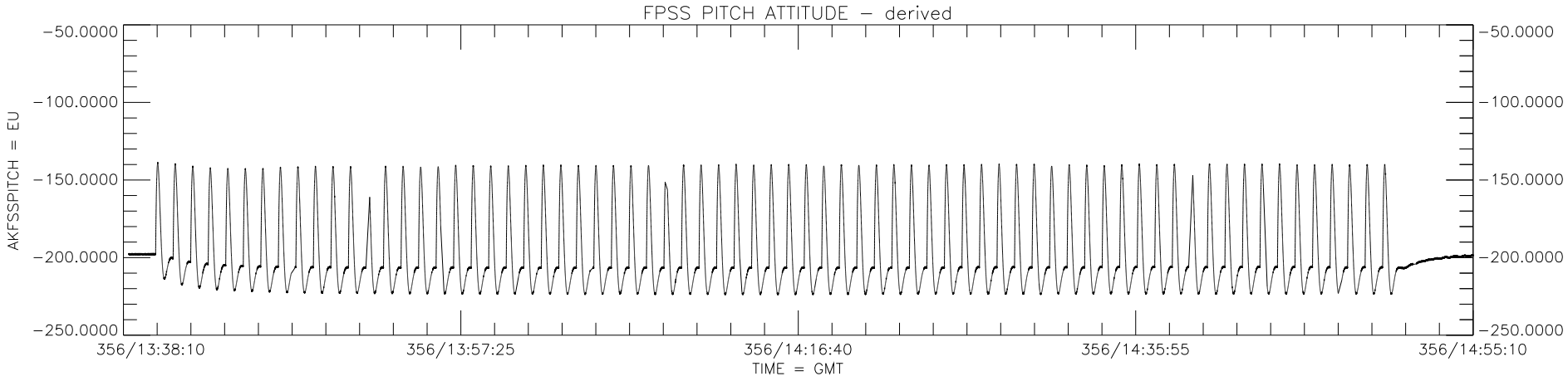
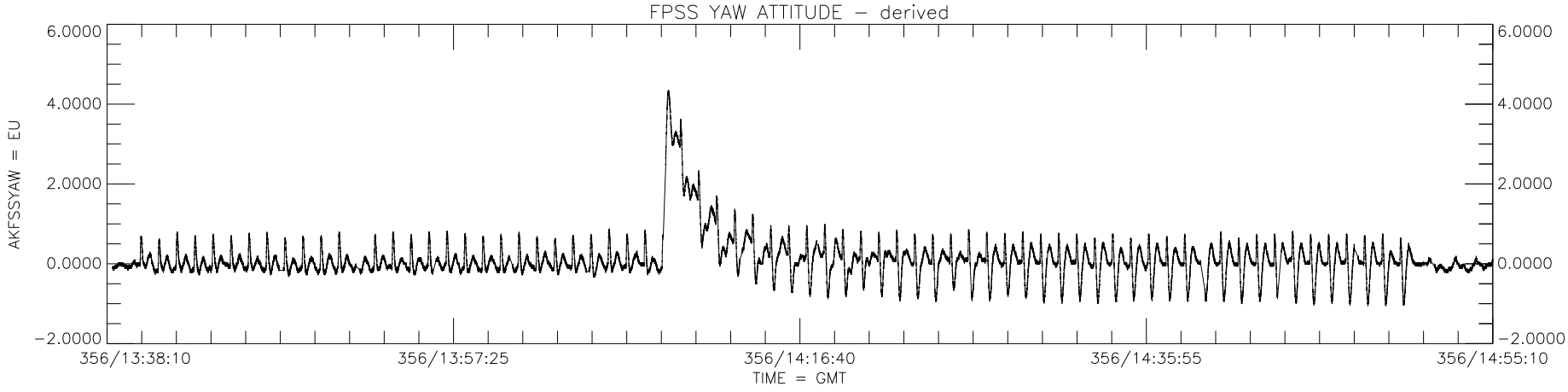

1−Hz roll attitude
AKROL = EU
−25390.0000
−25395.0000
−25400.0000
−25405.0000
356/13:38:10
356/13:57:25
356/14:16:40
356/14:35:55
356/14:55:10
TIME = GMT


FPSS PITCH ATTITUDE − derived
AKFSSPITCH = EU
−50.0000
−100.0000
−150.0000
−200.0000
−250.0000
356/13:38:10
356/13:57:25
356/14:16:40
356/14:35:55
356/14:55:10
TIME = GMT


FPSS YAW ATTITUDE − derived
AKFSSYAW = EU
6.0000
4.0000
2.0000
0.0000
−2.0000
356/13:38:10
356/13:57:25
356/14:16:40
356/14:35:55
356/14:55:10
TIME = GMT