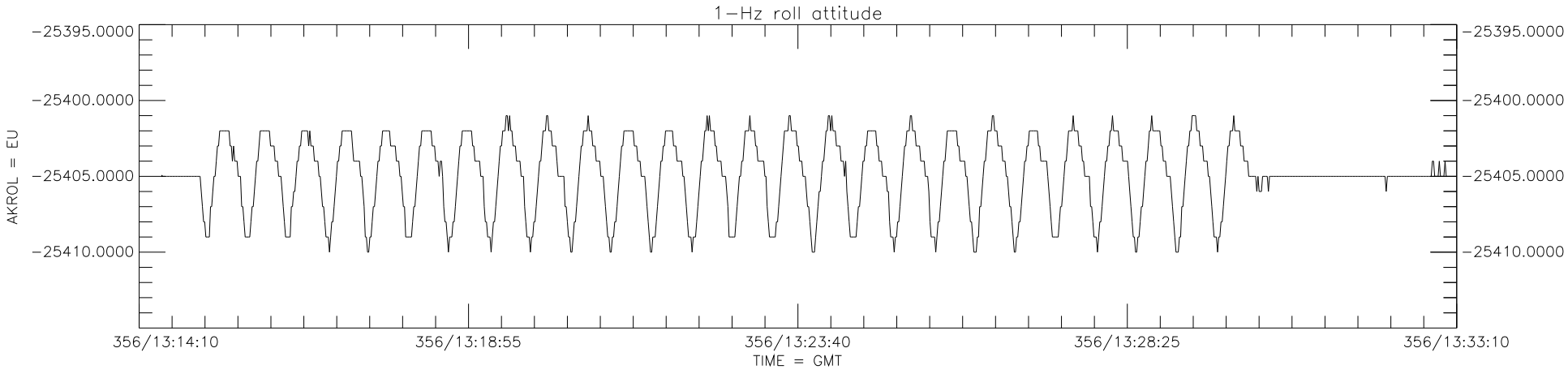
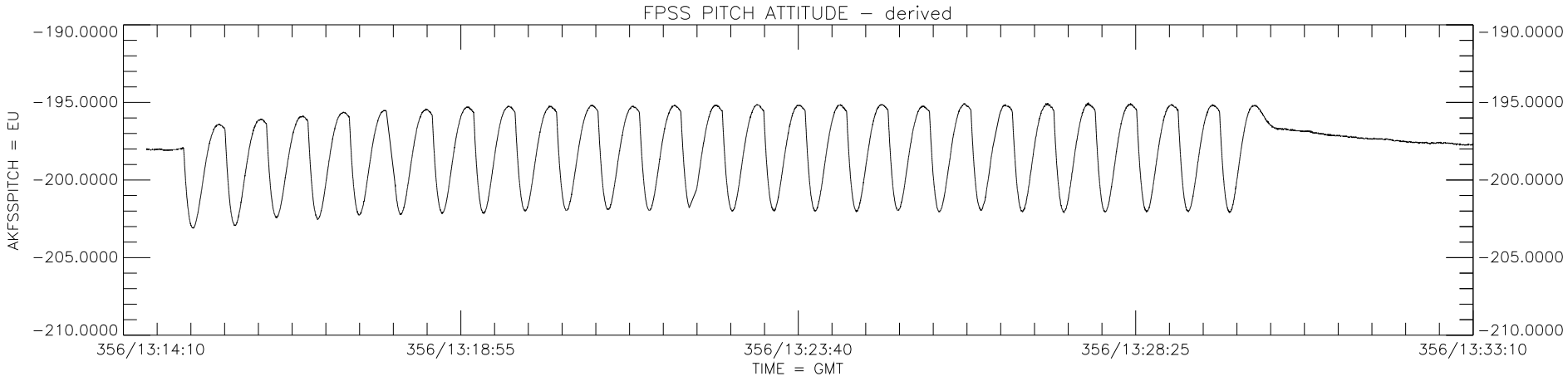
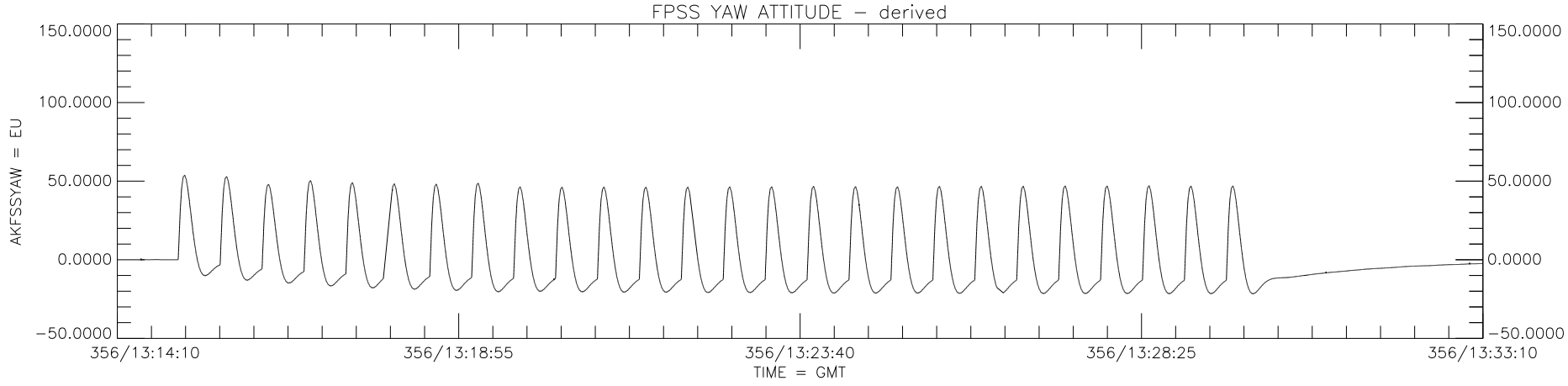

1−Hz roll attitude
AKROL = EU
−25395.0000
−25400.0000
−25405.0000
−25410.0000
356/13:14:10
356/13:18:55
356/13:23:40
356/13:28:25
356/13:33:10
TIME = GMT


FPSS PITCH ATTITUDE − derived
AKFSSPITCH = EU
−190.0000
−195.0000
−200.0000
−205.0000
−210.0000
356/13:14:10
356/13:18:55
356/13:23:40
356/13:28:25
356/13:33:10
TIME = GMT


FPSS YAW ATTITUDE − derived
AKFSSYAW = EU
150.0000
100.0000
50.0000
0.0000
−50.0000
356/13:14:10
356/13:18:55
356/13:23:40
356/13:28:25
356/13:33:10
TIME = GMT